

## Simulations of Mechanized Planting

-Modelling Terrain and Crane-Mounted Planting Devices

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#### Overview

- 1. Background
- 2. Objective
- 3. Materials and Methods
- 4. Results
- 5. Summary

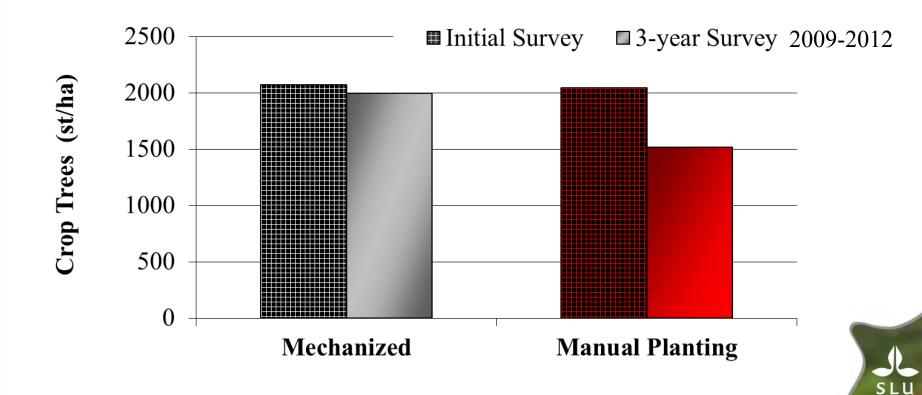




### Why Mechanized Tree Planting?

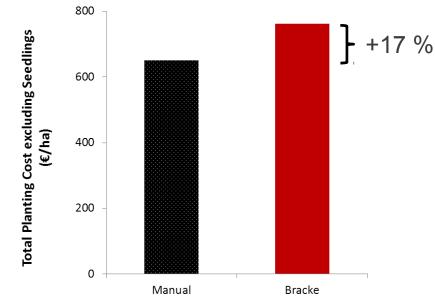
#### Better planting quality

- Spot mounding, deep planting, educated operators



### Planting Machines in Sweden Today





Mean Values for Södra Skog 2006-2011

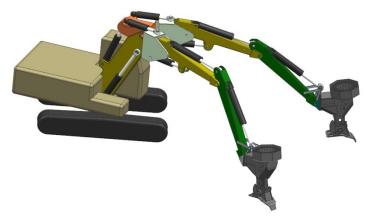


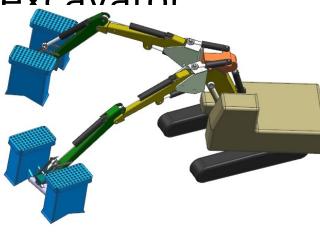
### How to Increase Productivity?

#### One Two heads per device



#### - One I Two arms per excavator

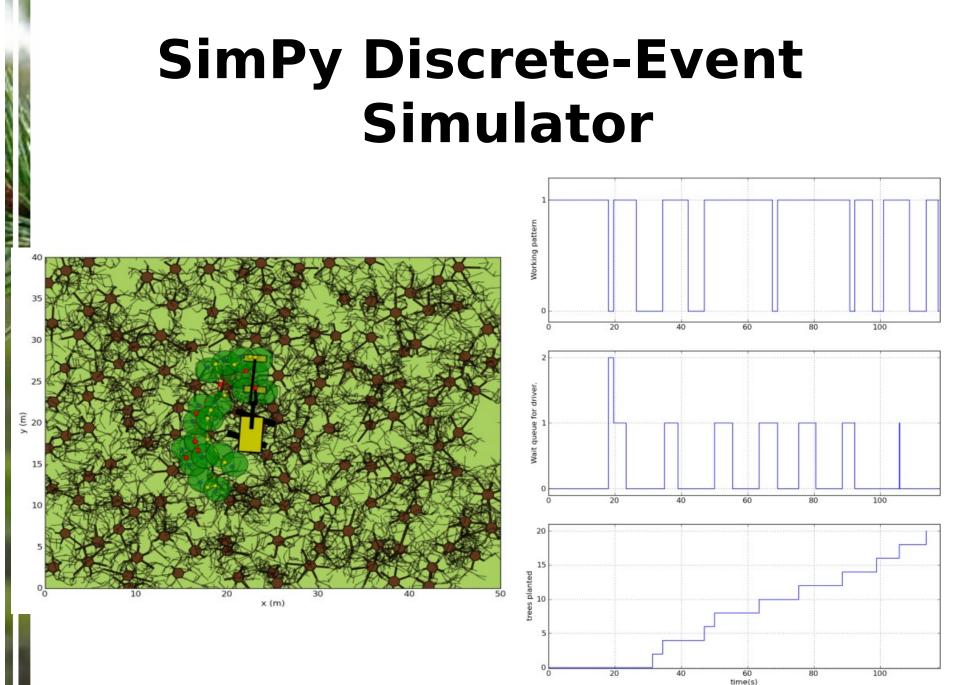


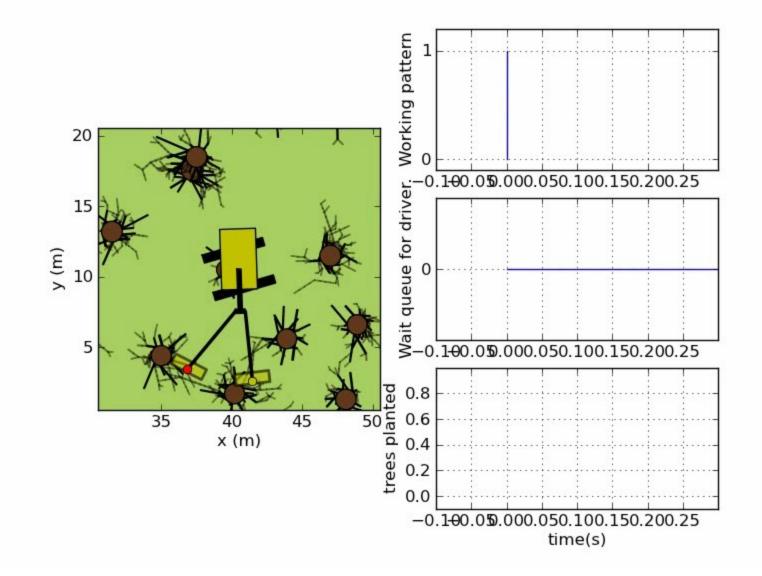


## Objective

Determine if 2-armed excavators are potentially more than just Science Fiction!

 Under Nordic clearcut conditions = various quantities, distributions and sizes of stones, roots and stun

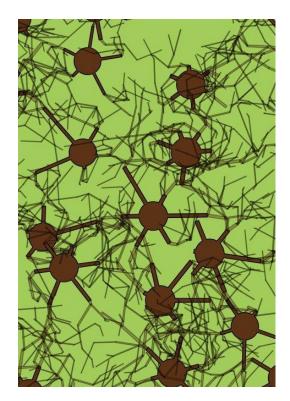


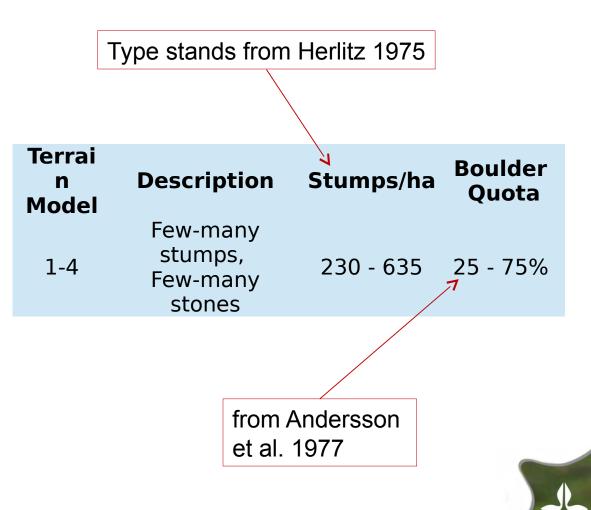




# **Materials and Methods Three main models:** 2. Machine 1. Terrain + 3. Simulation SLU

### **Terrain Models**

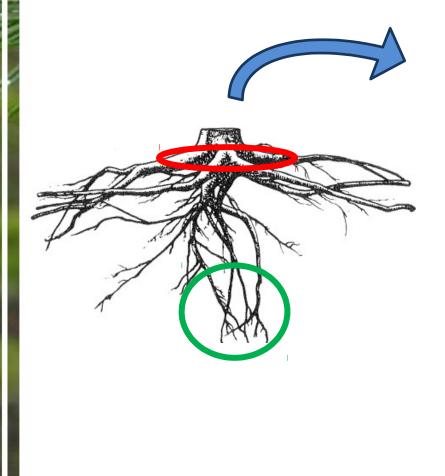


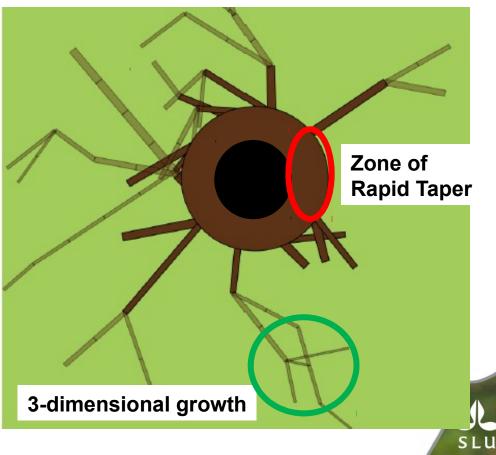


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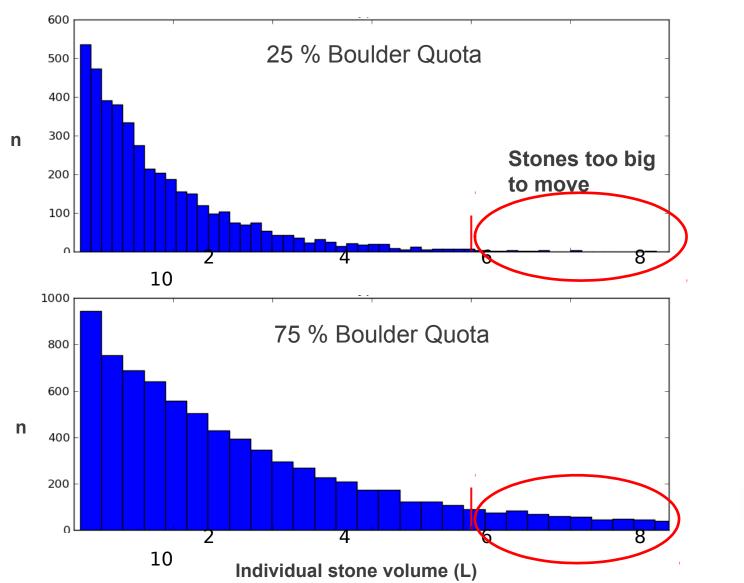
#### Stumps, Root Plates & Roots

Input: Dbh, DStump & species





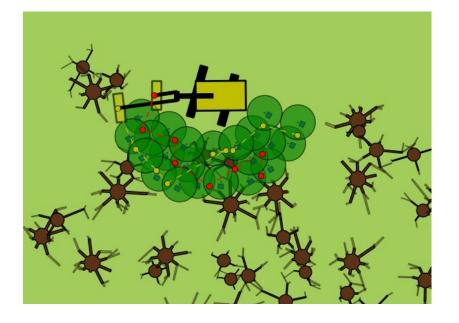
#### Comparing the Number of Immobile Stones on Terrain with 25% or 75% Boulder Ouota

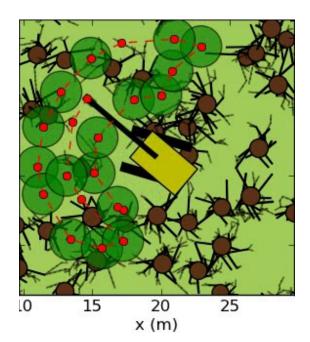


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### **Machine Models**

- 1- and 2-armed models
- With autonomous functions for mounding, planting and some crane movements
- 4 main tasks: moving crane, choosing microsites, mounding, planting

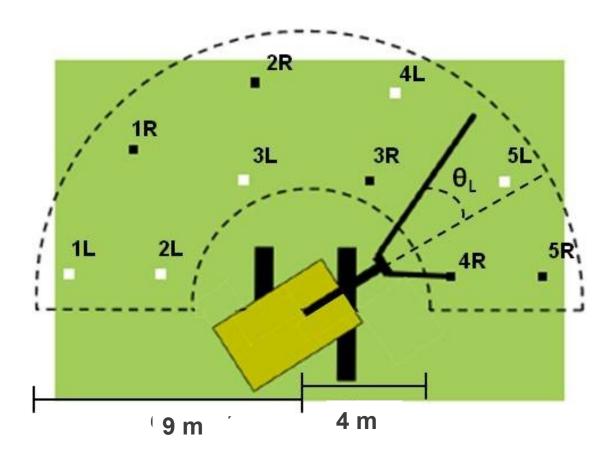






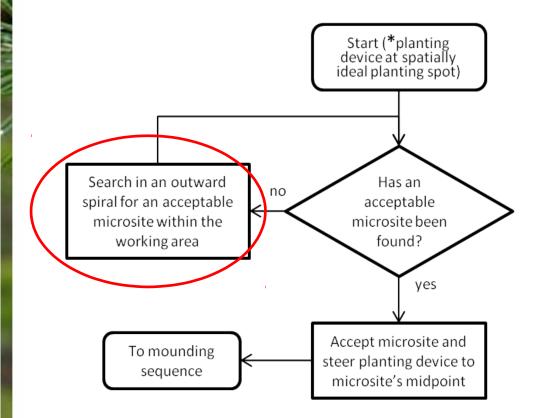
### **Simulation Models**

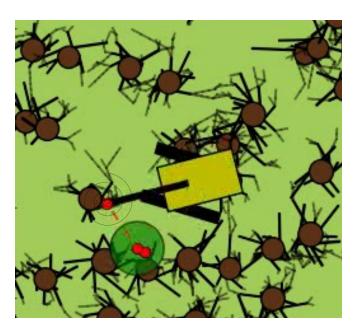
#### Working area & Work pattern





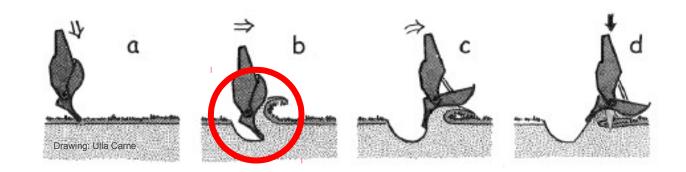
### Microsite Selection Algorithm



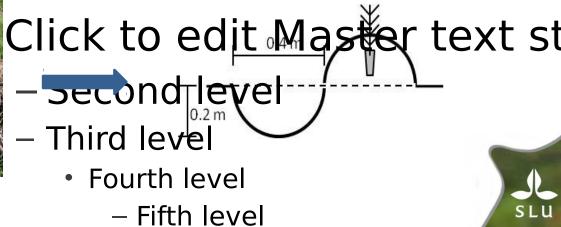




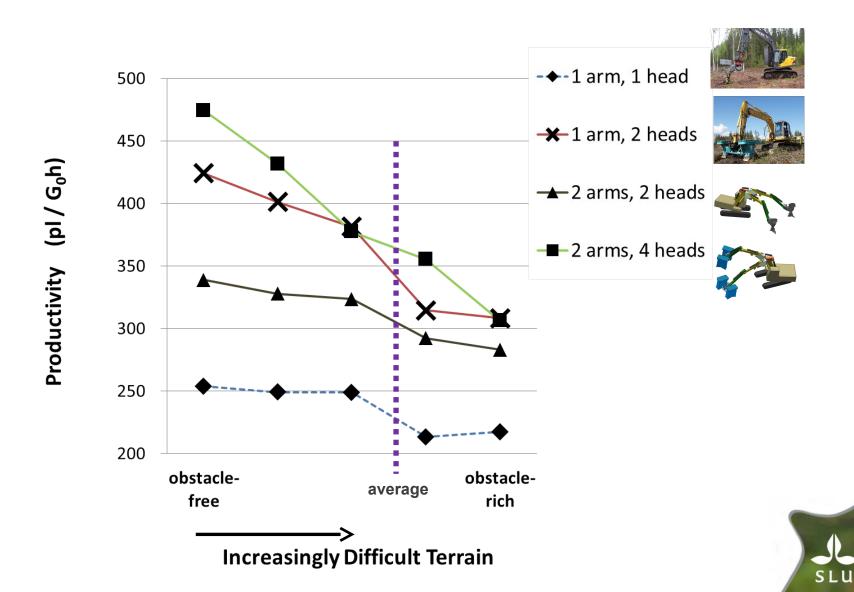
### Mounding and Planting



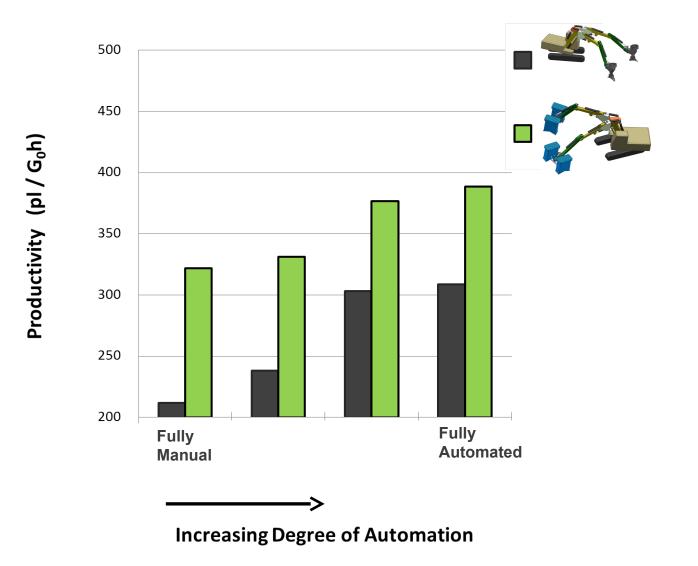




#### Results



#### **Effect of Automation on 2armed Machine Productivity**

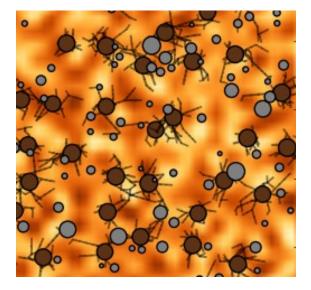




### Summary

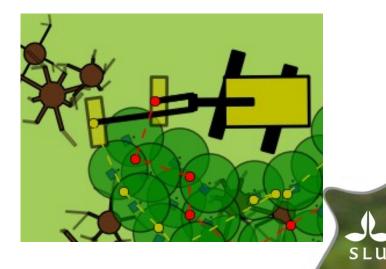
#### 1. Functional terrain models

- Now with stumps, roots, stones, surface boulders and variable humus depth



#### 3. Detailed machine models

- which interact with the terrain during scarification and planting



# **Paldies!**



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