

Simulations of Mechanized Planting

-Modelling Terrain and Crane-Mounted Planting Devices

Back Tomas Ersson1, Linus Jundén2, Urban Bergsten3 & Martin Servin2

1 Dept. of Forest Resource Management, SLU, Umeå

2 UMIT Research Lab, Umeå University

3 Dept. of Forest Ecology and Management, SLU, Umeå 🛞 SÖDRA FRST

Overview

- 1. Background
- 2. Objective
- 3. Materials and Methods
- 4. Results
- 5. Summary

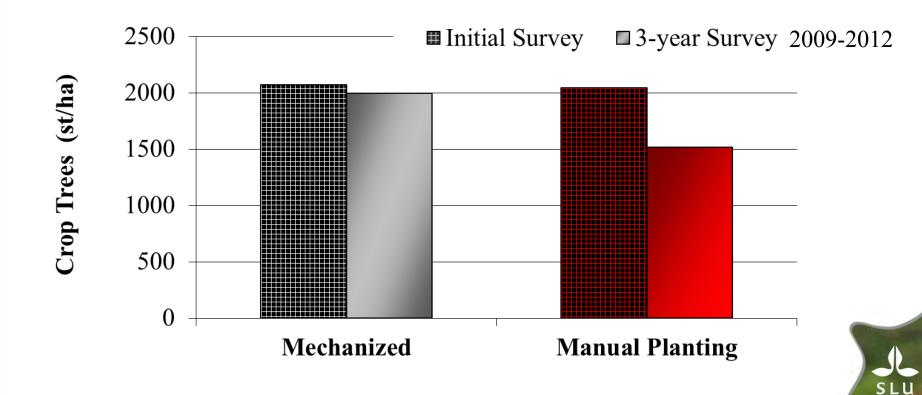




Why Mechanized Tree Planting?

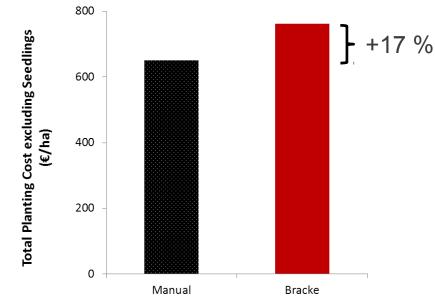
Better planting quality

- Spot mounding, deep planting, educated operators



Planting Machines in Sweden Today





Mean Values for Södra Skog 2006-2011

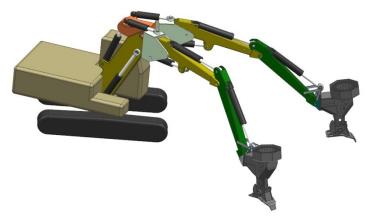


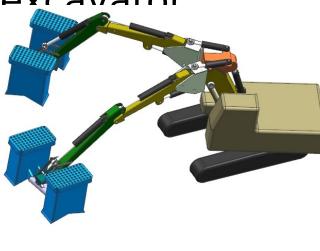
How to Increase Productivity?

One Two heads per device



- One I Two arms per excavator

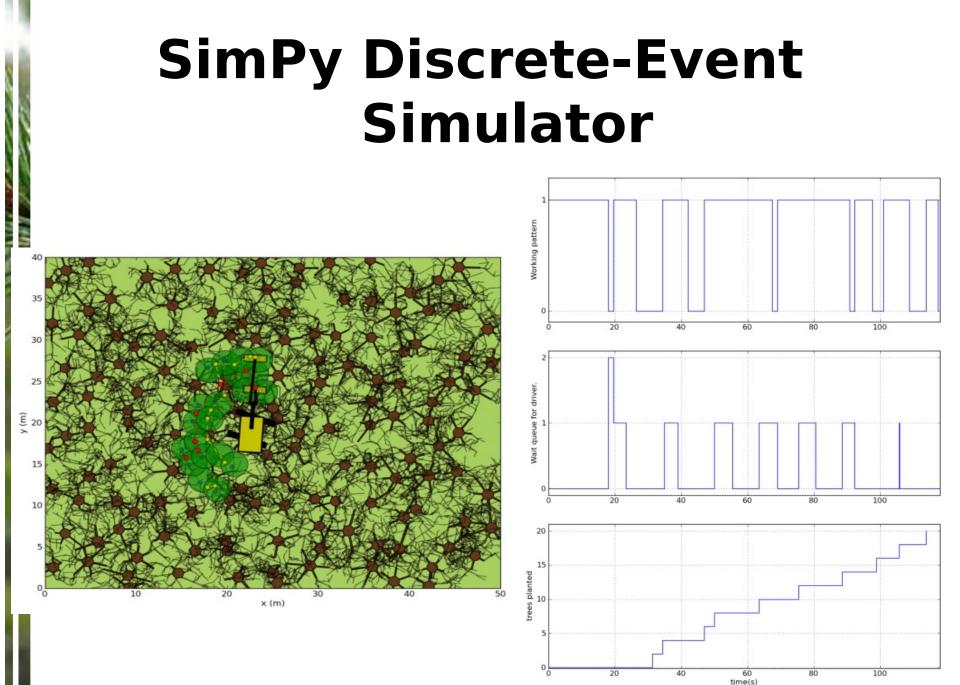


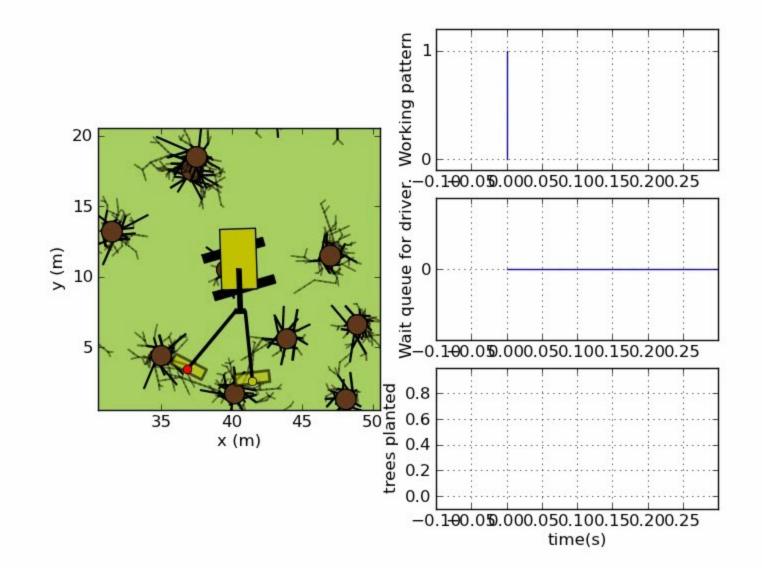


Objective

Determine if 2-armed excavators are potentially more than just Science Fiction!

 Under Nordic clearcut conditions = various quantities, distributions and sizes of stones, roots and stun

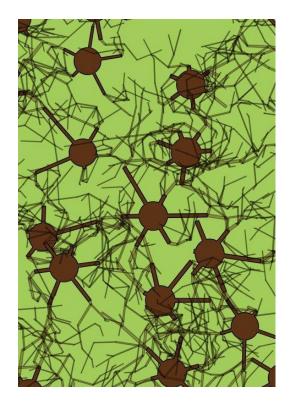


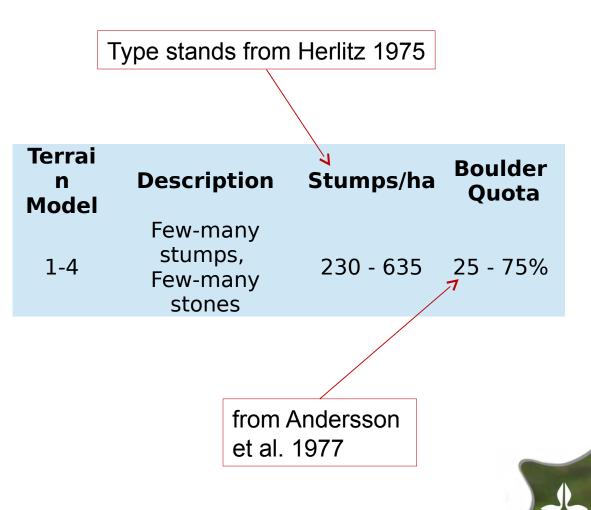




Materials and Methods Three main models: 2. Machine 1. Terrain + 3. Simulation SLU

Terrain Models

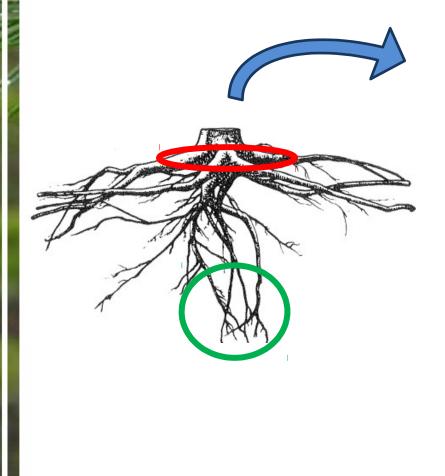


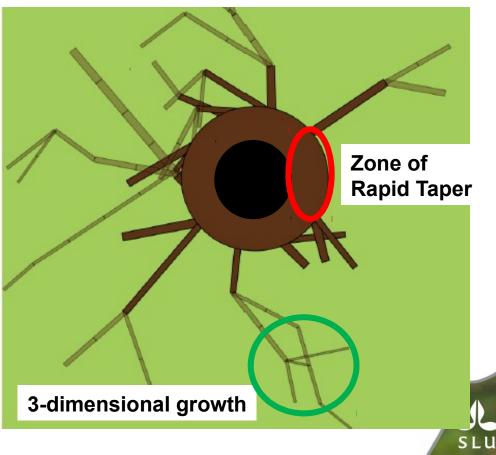


SLU

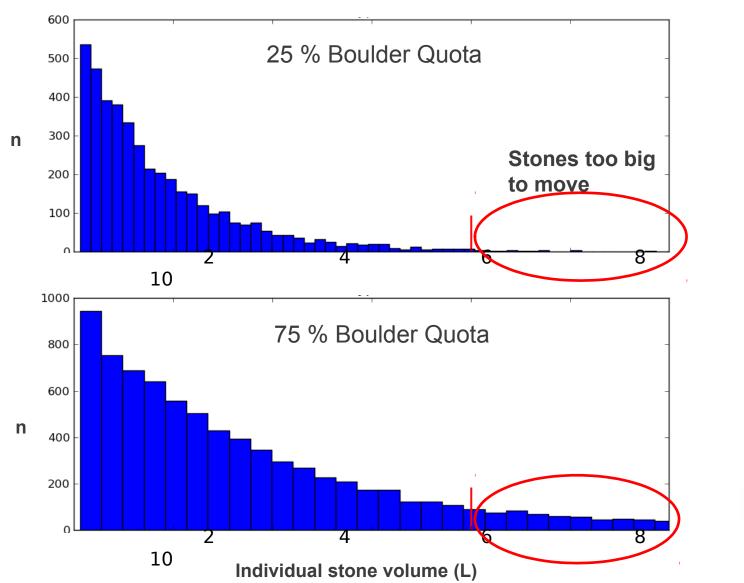
Stumps, Root Plates & Roots

Input: Dbh, DStump & species





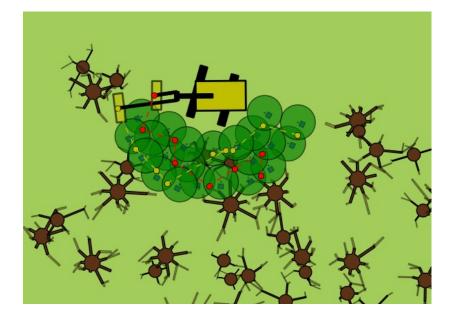
Comparing the Number of Immobile Stones on Terrain with 25% or 75% Boulder Ouota

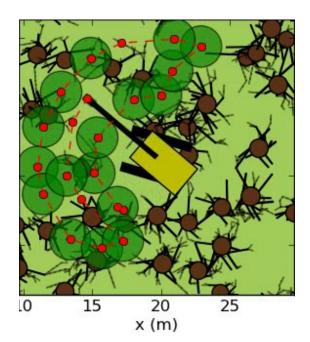


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Machine Models

- 1- and 2-armed models
- With autonomous functions for mounding, planting and some crane movements
- 4 main tasks: moving crane, choosing microsites, mounding, planting

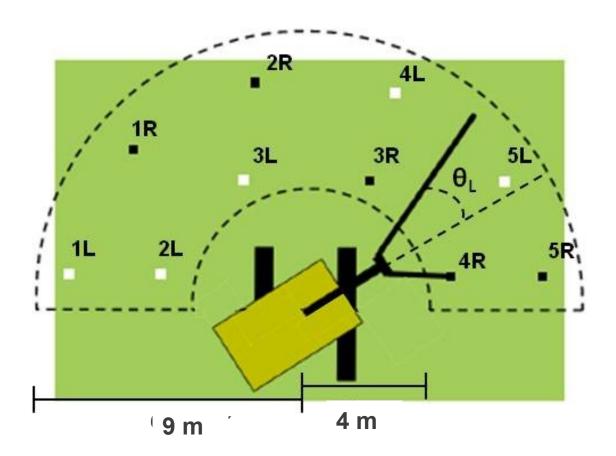






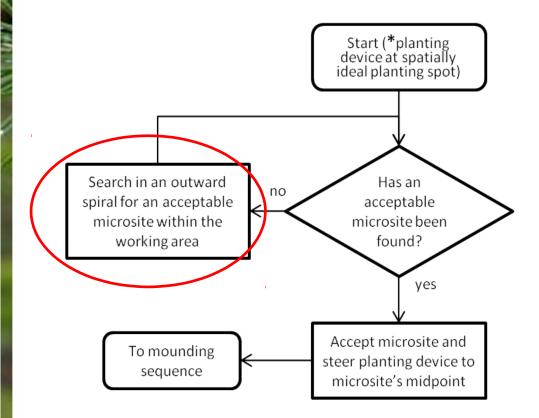
Simulation Models

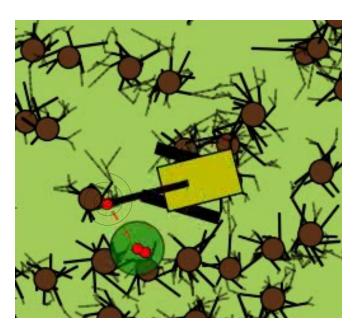
Working area & Work pattern





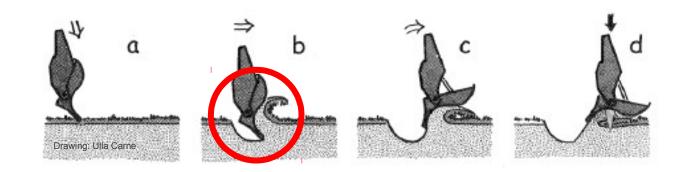
Microsite Selection Algorithm



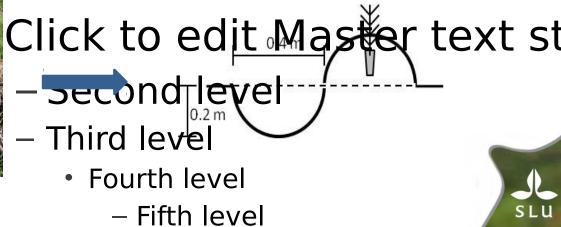




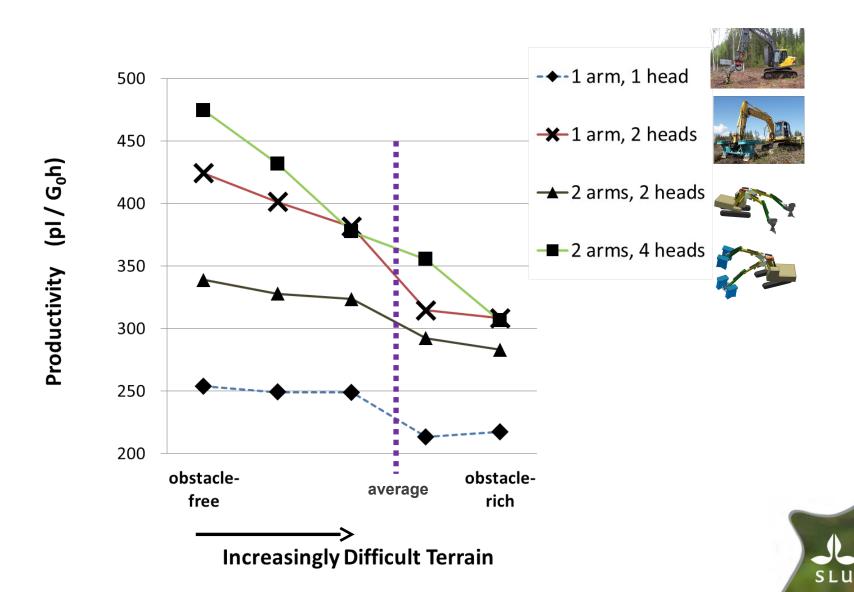
Mounding and Planting



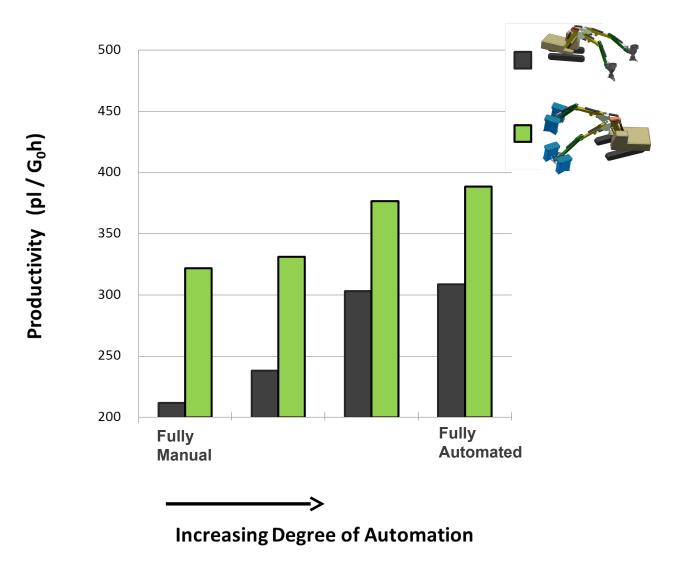




Results



Effect of Automation on 2armed Machine Productivity

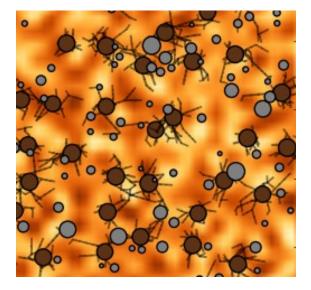




Summary

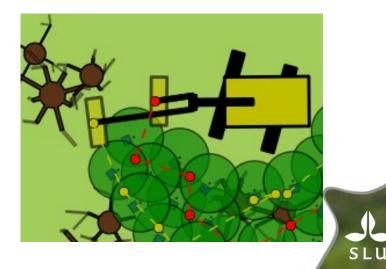
1. Functional terrain models

- Now with stumps, roots, stones, surface boulders and variable humus depth



3. Detailed machine models

- which interact with the terrain during scarification and planting



Paldies!



Back Tomas Ersson

PhD student Dept of Forest Resource Management

SLU

S-901 83 Umeå

back.tomas.ersson@slu.se

